

Week 16

①

June 8, 10.

Note The last class of this semester is June, 15th.
There is no class on the 17th.

(*) The 3rd test will be held on the 22nd of June.

(**) You shall know your grades on the 24th of June
before noon. please go over to the assistant to check.

Gram-Schmidt Orthogonalization Process

Part II, knowing the basis for the subspace

Theorem Let $B_1 = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$ be a basis for $W \subseteq \mathbb{R}^m$.

Then, there exists an orthonormal basis $B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$

for W such that \vec{v}_i is a linear combination of $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_i$

for each $i = 1, 2, \dots, n$.

Proof. By induction on n .

For $n=1$, let $\vec{v}_1 = \frac{\vec{u}_1}{\|\vec{u}_1\|}$ and we have the proof.
(assertion is true for $n=1$.)

Assume the assertion is true for $n=k$ and let $(k \geq 2)$

$$\vec{v}_k = \vec{u}_k - \langle \vec{v}_1, \vec{u}_k \rangle \vec{v}_1 - \langle \vec{v}_2, \vec{u}_k \rangle \vec{v}_2 - \dots - \langle \vec{v}_{k-1}, \vec{u}_k \rangle \vec{v}_{k-1}$$

(2)

Now, consider

$$\vec{w}_{k+1} = \vec{u}_{k+1} - \langle \vec{v}_1, \vec{u}_{k+1} \rangle \vec{v}_1 - \dots - \langle \vec{v}_k, \vec{u}_{k+1} \rangle \vec{v}_k.$$

For each $1 \leq j < k+1$,

$$\langle \vec{v}_{k+1}, \vec{v}_j \rangle = \langle \vec{u}_{k+1}, \vec{v}_j \rangle - \langle \vec{v}_j, \vec{u}_{k+1} \rangle \langle \vec{v}_j, \vec{v}_j \rangle = 0.$$

Hence $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ where $\vec{v}_{k+1} = \frac{\vec{w}_{k+1}}{\|\vec{w}_{k+1}\|}$ is an orthonormal ~~basis~~ ^{set} of vectors.

Moreover,

\vec{w}_{k+1} (\vec{v}_{k+1}) is a linear combination of vectors

$\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ and thus $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_{k+1}$.

This concludes the proof. ■

Example $B_1 = \left\{ \begin{matrix} \vec{u}_1 & \vec{u}_2 & \vec{u}_3 \\ (2, 0, 2, 1), & (0, 0, 4, 1), & (8, 0, 3, 5) \end{matrix} \right\}$

$$\vec{v}_1 = \frac{1}{3} (2, 0, 2, 1) \quad (?).$$

$$\vec{w}_2 = (0, 0, 4, 1) - 3 \left(\frac{2}{3}, 0, \frac{2}{3}, \frac{1}{3} \right) = (-2, 0, 2, 0).$$

$$\vec{v}_2 = \frac{\vec{w}_2}{\|\vec{w}_2\|} = \left(-\frac{\sqrt{2}}{2}, 0, \frac{\sqrt{2}}{2}, 0 \right).$$

$$\vec{w}_3 = \vec{u}_3 - \langle \vec{v}_1, \vec{u}_3 \rangle \vec{v}_1 - \langle \vec{v}_2, \vec{u}_3 \rangle \vec{v}_2$$

$$= \left(-\frac{1}{2}, 0, -\frac{1}{2}, 2 \right).$$

$$\vec{v}_3 = \frac{\sqrt{2}}{6} (-1, 0, -1, 4). \quad (\text{Check yourself!})$$

③

Example Find an O.N. basis for \mathbb{R}^3 which contains $\frac{1}{\sqrt{3}}(1, 1, 1)$ and $\frac{1}{\sqrt{2}}(1, -1, 0)$.

Sol. Find \vec{v}_3 only, $\vec{v}_3 = \frac{1}{\sqrt{6}}(-1, -1, 2)$.

Orthogonal Matrices

A matrix P (over \mathbb{R}) is orthogonal if $P^T = P^{-1}$.

(Note)

$$P^T P = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} \\ \vdots \\ \frac{1}{\sqrt{n}} \end{bmatrix} \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix}$$

$$= \begin{bmatrix} \langle \vec{v}_i, \vec{v}_j \rangle \end{bmatrix}_{n \times n} = I_n$$

$$\Rightarrow \langle \vec{v}_i, \vec{v}_j \rangle = 0 \text{ if } i \neq j \text{ and} \\ \langle \vec{v}_i, \vec{v}_i \rangle = 1 \text{ for } i = 1, 2, \dots, n.$$

(Over \mathbb{C})

$$P^* P = I$$

(Take transpose and conjugate.)

Definition

① Conjugate of A , $\bar{A} = [\bar{a}_{ij}]$, where $A = [a_{ij}]$, $a_{ij} \in \mathbb{C}$.

② Conjugate transpose of A , $A^* = [\bar{a}_{ij}]^T$.

Theorem All eigenvalues of a real symmetric matrix A are real.

Proof. Let λ be an eigenvalue of A . ($A: \mathbb{C}^n \rightarrow \mathbb{C}^n$)

Then $A\vec{x} = \lambda\vec{x}$, $\vec{x} \neq \vec{0}$ is an eigenvector associate with λ .

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\vec{x}^* A \vec{x} = \lambda \vec{x}^* \vec{x}$$

$$\vec{x}^* A^* \vec{x} = \lambda \vec{x}^* \vec{x} = \vec{x}^* A \vec{x} = (\vec{x}^* A \vec{x})^*$$

This implies that $\vec{x}^* A \vec{x}$ is real and thus

$$\lambda = \frac{\vec{x}^* A \vec{x}}{\vec{x}^* \vec{x}} \text{ is real.} \quad \square$$

Note Hermitian matrices

A matrix H (over F) is Hermitian if and only if $H^* = H$.

Theorem \forall Hermitian matrix H , \exists invertible matrix P such that $P^{-1} H P$ is a diagonal matrix.

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We prove the case when A is real symmetric.

(If A is real symmetric, then A is Hermitian.)

Theorem If A is a real symmetric matrix of order n , then there exists an orthogonal matrix P (over \mathbb{R}) such that $P^T A P$ is a diagonal matrix.

Proof. By induction on n and it is clear that " $n=1$ " is true. Assume that the assertion is true when $n=k$ and

let A be a real symmetric matrix of order $k+1$.

Let $\lambda_1 \in \mathbb{R}$ be an eigenvalue of A ^{with} corresponding eigenvector

\vec{v}_1 . By Gram-Schmidt process, we have an orthonormal basis

$B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k+1}\}$ for \mathbb{R}^{k+1} . Now, let $P_1 = [\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{k+1}]$.

Then $P_1^T A P_1 = \begin{bmatrix} \vec{v}_1^T A \vec{v}_1 \\ \vdots \\ \vec{v}_{k+1}^T A \vec{v}_{k+1} \end{bmatrix}_{(k+1) \times (k+1)}$. By the fact that $A \vec{x}_1 = \lambda_1 \vec{x}_1$,

we have

$$P_1^T A P_1 = \begin{bmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & & & & \\ 0 & & & & \\ \vdots & & & & \\ 0 & & & & \end{bmatrix} \cdot$$

(b)

$$(*) \quad \vec{v}_i^T A \vec{v}_j = (\vec{v}_j^T A \vec{v}_i)^T = (\vec{v}_j^T (\lambda_i \vec{v}_i))^T = \lambda_i (\vec{v}_j^T \vec{v}_i)^T = 0 \quad (j \neq i)$$

$$\vec{v}_i^T A \vec{v}_i = \vec{v}_i^T (\lambda_i \vec{v}_i) = \lambda_i \vec{v}_i^T \vec{v}_i = 0 \quad (i \neq 1).$$

(**) A_2 is a real symmetric matrix of order k .

By induction hypothesis, $\exists Q$ (orthogonal matrix of order k), such that

$$Q^T A_2 Q = \begin{bmatrix} \lambda_2 & & & 0 \\ & \ddots & & \\ 0 & & & \lambda_{k+1} \end{bmatrix}.$$

($\lambda_2, \dots, \lambda_{k+1}$ are eigenvalues of A_2 .)

Now, let $P_2 = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & & & & \\ \vdots & & Q & & \\ 0 & & & & \end{bmatrix}$ and $P = P_1 P_2$.

Then, $P^T A P = (P_1 P_2)^T A (P_1 P_2)$

$$= P_2^T (P_1^T A P_1) P_2$$

$$= P_2^T \begin{bmatrix} \lambda_1 & \vec{0}^T \\ \vec{0} & A_2 \end{bmatrix} P_2$$

$$= \begin{bmatrix} 1 & \vec{0}^T \\ \vec{0} & Q^T \end{bmatrix} \begin{bmatrix} \lambda_1 & \vec{0}^T \\ \vec{0} & A_2 \end{bmatrix} \begin{bmatrix} 1 & \vec{0}^T \\ \vec{0} & Q \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 & \vec{0}^T \\ \vec{0} & Q^T A_2 Q \end{bmatrix} = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_{k+1} \end{bmatrix}. \quad \square$$

(Note) The proof for Hermitian matrices is similar.

Theorem If λ_1 and λ_2 are distinct eigenvalues of A (real symmetric) with associated eigenvectors \vec{v}_1 and \vec{v}_2 , respectively, then $\vec{v}_1 \perp \vec{v}_2$.
(*)

Proof.

Suppose not. Let $\langle \vec{v}_1, \vec{v}_2 \rangle \neq 0$.

Since $A\vec{v}_1 = \lambda_1\vec{v}_1$ and $A\vec{v}_2 = \lambda_2\vec{v}_2$,

$$\vec{v}_1^T A \vec{v}_2 = \vec{v}_1^T \lambda_2 \vec{v}_2 = \lambda_2 \vec{v}_1^T \vec{v}_2; \text{ and}$$

$$(\vec{v}_1^T A \vec{v}_2)^T = \vec{v}_2^T A \vec{v}_1 = \lambda_1 \vec{v}_2^T \vec{v}_1.$$

$$(\lambda_1 \vec{v}_2^T \vec{v}_1)^T = \lambda_1 \vec{v}_1^T \vec{v}_2 = \lambda_2 \vec{v}_1^T \vec{v}_2,$$

This implies that $\lambda_1 = \lambda_2$, □